FASTRADE FPGA-Accelerated Strategy & Trading for Enhanced Decisions

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TRANSCENDING DISCIPLINES, TRANSFORMING LIVES



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Factor Model: Multi-Factor Model (5 Raw Features + 4 Factors)

Reference:

[Rendle, 2010] Steffen Rendle. Factorization machines. In ICDM, 2010. •



• FPGAs are widely used at quant companies.

But quantitative researchers prefer Python.

We are interested to reproduce the investment pipeline on FPGA



Outcome

A Well Composed End-2-End Multi-Factor Investment Pipeline :

- Components:Hardware Factor Calculation, Software model training/inference
- Well designed Hardware/Software data interfaces
- User-Friendly VGA display and Keyboard interaction.
- Verified hardware calculation waveform and acceleration improvement

End2End System Overview





Detailed System Design





7 | Introduction

Hardware - Software Interfaces

e <u>E</u> dit <u>S</u> ystem <u>G</u> enerate <u>V</u> iew <u>T</u> ools <u>H</u> elp						Component Editor - vga_ball_hw.tcl*
IP Catalog 🕴 🗕 📑 🖬	System Contents 🕱 Address Map 🛞 Interconn	act Requirements 😂				<u>E</u> ile Iemplates <u>B</u> eta <u>V</u> iew
	System: soc system Path: clk 0					Component Type 💠 Block Symbol 🔅 Files 🔅 Parameters 🍀 Signals & Inter
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roject → Wew Component → Uther → Other → Date → Basic Functions → DSP → Basic Functions → DSP → Interface Protocols → Low Prover → Memory Interfaces and Controllers → Processors and Peripherals → Pro	Characterise Charact	Clock Structure ck Paset Input che Paset Output pastic Reset Output pastic Clock Output pastic Reset Output pastic Clock Output pastic Clock Output pastic Clock Input pastic Clock Output pastic Clock Input Double Clock Input Double Clock Input Double Clock Input Double VGA Ball Double Clock Input Double VGA Ball Double Conduit Double VGA Ball Double Conduit Double VGA Ball Double Conduit Double Vga Double Vga Double Vga Double	ecitick to exported >>click to clk_0 >>click to clock) >>> clock)	0000 1FQ / 1FQ /	0x 0000_003f	Name ■ valon, slave, 0. Avalon. Memory. Mapp ■ valon, slave, 0. Avalon. Memory. Mapp ■ chipselect [1]. robolect ■ readiata [16] readdata • or radiata • or rest [1] reset • or radiata • or radiata



addr 0	addr 1	addr 2	addr 3	addr 4	addr 5	add	r 6	addr 17	addr 18	addr 19
Status	Actual Return	Actual Return	IC	IC	IC	Sigi	n	Factor	Factor	Cursor
				Bit 0		Bit ²	1			
				Sign for Actual Return		urn	Sigr	n for Facto	r	



Write to Hardware

addr 7	addr 8	addr 9	addr 10	addr 11
Open	High	Low	Close	Volume

Read from Hardware

addr 12	addr 13	addr 14	addr 15	addr 16
Momentum	Volume	RSI	MA	Done



This module was designed for signed division of fixed-point numbers.

Inputs: Dividend, Divisor Outputs: Quotient, Signal Completion, Busy, Divide by zero flag

Used Gaussian Rounding to implement the module and handled some special cases, including divided by zero.

Calculator Module

This module was designed to calculate the factors.

Use a 2D register array to store the original data and the calculation results(factors).

The hardware will read or write data according to the signals.

Only when all the five base data have been received, the module will start to calculate the factors.

Only when all the factors of one day have been calculated, the software part can read the results.



Calculator



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- Resolution: 680 * 480
 - 80 columns, 60 rows
- 50 character bitmaps: 8 * 8 bits/each
- Efficient storage(only store bitmaps)

char_a[0]	=	8'b00011000;	11	**	
char_a[1]		8'b00100100;			
char_a[2]		8'b01000010;			
char_a[3]		8'b01111110;			
char_a[4]		8'b01000010;			
char_a[5]		8'b01000010;			
char_a[6]		8'b01000010;			
char_a[7]		8'b01000010;			
char_b[0]		8'b01111100;			
char_b[1]		8'b01000010;			
char_b[2]		8'b01000010;			
char_b[3]		8'b01111100;			
char_b[4]		8'b01000010;			
char_b[5]		8'b01000010;			
char_b[6]		8'b01000010;			
char_b[7]		8'b01111100;			
char_c[0]		8'b00111100;			
char_c[1]		8'b01000010;			
char_c[2]		8'b0100000;			
char_c[3]		8'b0100000;			
char_c[4]		8'b0100000;			
char_c[5]		8'b0100000;			
char_c[6]		8'b01000010;			
char_c[7]		8'b00111100;			



		260,000 260,000 265,000	270,000 275,000 2	80,000 285,000 290,000	295,000 310,000 305,000 310,000
Ð	address[4:0]	2 12 0 1	2 3	4 5 6 11	12
	clk				
	reset	0	فالمستعلق المستخصا		
	write	0			
Ð	writedata[15:0]	0 1 2	jo (1	2 3 0 2	
Ð	address[4:0]	2 12 0 11	2 (3)4 (5 (6)11	12
Ð	actual_value1[7:0]	2 0	2		
Ð	actual_value2[7:0]	0 2	0		
Ð	ic1[7:0]	3 3	(1		
Ð	ic2[7:0]	4 4		2	
Ð	ic3[7:0]	5 5		3	
Ð	sign[1:0]	1 1		,o	
Ð	factor_value1[7:0]	1 1			2
Ð	factor_value2[7:0]	1 1			2

Note: To revert to EPWave opening in a new browser window, set that option on your profile page





Software

• Factor Model





Everything works fine on Python, yet hard to program in C.

Reproduced every from scrach by stand C libs. Lack of machine learning libs: ->

```
#ifndef MATRIX H
#define MATRIX H
typedef struct {
  double **data:
  int rows;
  int cols;
} Matrix;
Matrix create_matrix(int rows, int cols);
void free_matrix(Matrix m);
Matrix multiply matrices(Matrix a, Matrix b);
void elementwise multiply(Matrix a, Matrix b, Matrix result);
double sum matrix elements(Matrix m);
void init random normal(Matrix m, double mean, double stddev);
double sigmoid(double x);
void compute_means(Matrix features, double *means);
void compute_stddevs(Matrix features, double *means, double
*stddevs);
void standardize_features(Matrix features, double *means, double
*stddevs):
                                                                                *active_features);
double pearson_correlation(double *x, double **y, int n);
#endif
```

```
// fm model.h
#ifndef FM MODEL H
#define FM_MODEL_H
#include "matrix.h"
#include <stdbool.h>
typedef struct {
 double bias: // Scalar bias term w0 in the model
 Matrix weights; // Weight vector w in the model
 Matrix factors; // Factorization matrix V in the model
} FMModel:
void fit(FMModel *model, Matrix X, Matrix y, int feature_potential,
         double alpha, int iter, int batch size, double decay rate);
double *predict(FMModel *model, Matrix X);
double *predict active(FMModel *model, Matrix X, Matrix Ref ,bool
```

#endif



Everything works fine on Python, yet hard to program in C.

Overflow during gradient descent: -> Improved Training Strategy

- Various Feature Scale, too large data:
 - Zscore Normalization

- Overflow caused by gradient accumulation:
 - Mini-batch Gradient Descent
 - Learning Rate decay



Evaluation

• Hardware(Python runs on Google Colab)

Calculation Time using Python(Colab)	Calculation Time using Python(M1)	Calculation Time using SV
0.0050289 s	0.0014479 s	0.0018 s

• Software

Python Training	Python Inference	Python Training	Python Inference	On Board Training	On Board Inference
/20epoch(Colab)	Time(Colab)	/20epoch(M1)	Time(M1)	/20epoch	Time
1.103962 s	0.000150 s	0.225156 s	0.000026 s	0.130262 s	0.000035 s

*M1 refers to Apple M1 Pro and Colab refers to Google Colab's CPU



Demo

- Blue current place of cursor
- Green selected features
- Train train the model
- Test prediction

- Press \uparrow and \downarrow to move cursor
- Press enter to select/unselect feature





TRANSCENDING DISCIPLINES, TRANSFORMING LIVES

